## Flight test report

Manufacturer Gin Gliders

Address 586-5 Ilsan-Ri, Mohyun-Myun

Yongin City Kyunggi-Do 449-855

Korea

Representive Housi Bollinger
Type of glider Yeti 22
Trimmer not available

Certification number
Date of flight test
Place of test

PG 114.2007 08/02/2008 Monaco/Villeneuve



## Classification B

Test Pilot Tim Bollinger Harness Sup'Air - Altiplume S

Total weight in flight 52 kg

Philippe Dupont Sup'Air - Access

65	ka

		Min weight	Max weight
1. Inflation/Ta			max noight
	Rising behaviour Special take off technique required	Smooth, easy and constant rising A	
2. Landing	Consist los discretas baixos as suited	No	Ma
3. Speed in st	Special landing technique required	No A	No /
J. Opecu III J	Trim speed more than 30 km/h	Yes A	Yes
	Speed range using the controls larger than 10 km/h	Yes	
	Minimum speed	Less than 25 km/h	
4. Control mo	vement		
	Max. weight in flight up to 80 kg		
	Symmetric control pressure/travel	Increasing, Greater than 55 cm	Increasing, Greater than 55 cm
	Max. weight in flight 80 kg to 100 kg		
	Symmetric control pressure/travel  Max. weight in flight greater than 100 kg	not available	0 not available
	Symmetric control pressure/travel	not available	0 not available
5. Pitch stabi	lity exiting accelerated flight	not available	The available
	Dive forward angle on exit	Dive forward less than 30°	Dive forward less than 30°
	Collapse occurs	No A	No /
6. Pitch stabi	lity operating controls during accelerated flight		
	Collapse occurs	No A	No /
'. Roll stabili	ty and damping	Deduction	Deductor
Ctobility !:	Oscillations	Reducing	Reducing
s. Stability in	gentle spirals  Tendency to return to straight flight	Spontaneous exit	Spontaneous exit
9 Rehaviour	in a steeply banked turn	Sportlaneous exit	Spontaneous exit
o. Benavioa	Sink rate after two turns	12 m/s to 14 m/s	More than 14 m/s
10. Symmetri	c front collapse		I More than 1 1 m/c
	Entry	Rocking back less than 45°	Rocking back less than 45°
	Recovery	Spontaneous in less than 3 s	Spontaneous in less than 3 s
	Dive forward angle on exit	Dive foward 0°to 30°, Keeping course	3
	Cascade occurs	No A	No /
	With accelerator		
	Entry	Rocking back less than 45°	
	Recovery	Spontaneous in less than 3 s  Dive foward 0°to 30°, Keeping course	
	Dive forward angle on exit Cascade occurs	Dive foward 0°to 30°, Keeping course  No  A	
11. Exitina de	ep stall (parachutal stall)	T T	7
	Deep stall achieved	Yes	Yes
	Recovery	Spontaneous in less than 3 s	Spontaneous in less than 3 s
	Dive forward angle on exit	Dive forward 0°to 30°	Dive forward 0°to 30°
	Change of course	Changing course less than 45°	
	Cascade occurs	No A	No /
12. High angl	e of attack recovery		
	Recovery	Spontaneous in less than 3 s	
12 Bosovoni	Cascade occurs from a developed full stall	No A	No No
io. Necovery	Dive forward angle on exit	Dive forward 0°to 30°	Dive forward 0°to 30°
	Collapse	No collapse A	
	Cascade occurs (other than collapse)	No A	•
	Rocking back	Less than 45°	Less than 45°
	Line tension	Most line tight	Most line tight
14. Asymmet			
	With 50% collapse-Maximum dive forward or roll angle	Land the or OOO Diversity 1 200 1 150	Lass the coop Piers are " Lass 150
	Change of course until re-inflation	Less than 90°, Dive or roll angle 0° to 15°  Spontaneous re inflation	
	Re-inflation behaviour Total change of course	Spontaneous re-inflation Less than 360°  A	·
	Collapse on the opposite side occurs	No A	
	Twist occurs	No A	
	Cascade occurs	No A	
	With 75% collapse-Maximum dive forward or roll angle	•	
	Change of course until re-inflation	Less than 90°, Dive or roll angle 15° to 45°	Less than 90°, Dive or roll angle 0° to 15°
	Re-inflation behaviour	Spontaneous re-inflation	
	Total change of course	Less than 360°	
	Collapse on the opposite side occurs	No A	
	Twist occurs	No A	
	Cascade occurs	No A	No /
	With 50% collapse and accelerator-Maximum dive forward of Change of course until re-inflation		Less than 90°, Dive or roll angle 0° to 15°
	Change of course until re-inflation  Re-inflation behaviour	Less than 90°, Dive or roll angle 0° to 15°  Spontaneous re-inflation	•
	Total change of course	Less than 360°	
	Collapse on the opposite side occurs	No A	
			.1

	Twist occurs	No		No	Α
	Cascade occurs	No	Α	No	Α
	With 75% collapse and accelerator-Maximum dive forward of				
	Change of course until re-inflation	90° to 180°, Dive or roll angle 0° to 15°		Less than 90°, Dive or roll angle 15° to 45°	Α
	Re-inflation behaviour	Spontaneous re-inflation	Α	Spontaneous re-inflation	Α
	Total change of course	Less than 360°	Α	Less than 360°	Α
	Collapse on the opposite side occurs	No	Α	No	Α
	Twist occurs	No	Α	No	Α
	Cascade occurs	No	Α	No	Α
15. Direction	al control with a maintained asymmetric collapse				
	Able to keep course	Yes	Α	Yes	Α
	180° turn away from the collapsed side possible in 10 s	Yes	Α	Yes	Α
	Amount of control range between turn and stall or spin	More than 50 % of the symmetric control travel	Α	More than 50 % of the symmetric control travel	Α
16. Trim spec	ed spin tendency				
	Spin occurs	No	Α	No	Α
17. Low spee	ed spin tendency				
	Spin occurs	No	Α	No	Α
18. Recovery	from a developed spin	0		0, 1, 1, 1, 1, 200	
	Spin rotation angle after release	Stops spinning in less than 90°	Α	Stops spinning in less than 90°	Α
	Cascade occurs	No	Α	No	Α
19. B-line sta					
	Change of course before release	Change of course less than 45°	Α	Change of course less than 45°	Α
	Behaviour before release	Remains stable with straight span	Α	Remains stable with straight span	Α
	Recovery	Spontaneous in less than 3 s	Α	Spontaneous in less than 3 s	Α
	Dive forward angle on exit	Dive forward 0° to 30°	Α	Dive forward 0° to 30°	Α
aa B:	Cascade occurs	No	Α	No	Α
20. Big ears		5		0	
	Entry procedure	Dedicated controls	Α		Α
	Behaviour during big ears	Stable flight	A	Stable flight	A
	Recovery	Spontaneous in less than 3 s	A	Spontaneous in less than 3 s	A
04 Bin	Dive forward angle on exit	Dive forward 0° to 30°	Α	Dive forward 0° to 30°	Α
21. Big ears	in accelerated flight	De d'este desentado		Oten dend to the image	
	Entry procedure	Dedicated controls		Standard technique	Α
	Behaviour during big ears	Stable flight Spontaneous in less than 3 s	A A	Stable flight Spontaneous in less than 3 s	A A
	Recovery	•	A	Dive forward 0° to 30°	
	Dive forward angle on exit	Dive forward 0° to 30°			A
22 Dahardan	Behaviour immediately after releasing the accelerator while	Stable flight	Α	Stable flight	Α
22. Benaviou	r exiting a steep spiral	Constanting and	۸	Coordonosia suit	٨
	Tendency to return to straight flight	Spontaneous exit	A	Spontaneous exit	A
	Turn angle to recover normal flight	Less than 720°,spontaneous recovery 16 m/s	Α	Less than 720°,spontaneous recovery 14 m/s	Α
22 Altaunati	Sink rate when evaluating spiral stability [m/s] ye means of directional control	16 111/8		14 III/S	
23. Alternativ		Yes	۸	Yes	^
	180° turn achievable in 20 s		Α		A
04 A 41 4	Stall or spin occurs	No	Α	No	Α
24. Any other	r flight procedure and/or configuration described in the us		_	not available	^
	Procedure works as described	not available	_	11010101010	0
	Procedure suitable for novice pilots Cascade occurs	not available not available	0	not available not available	0
Comments		HUL avallable	0	not available	U
Comments o	Comments	Manufacturar pilot flying under radio access by		no	
	Comments	Manufacturer pilot flying under radio control by Alain Zoller, same as SIV course.		110	
		Main Zuier, Salle as SIV Course.			



Air Turquoise
Rue de la Poterlaz 6
Case postale 10
CH- 1844 Villeneuve
Switzerland
mobile: +41 79 202 52 30
Tel. no: +41 21 965 65 65
fax: +41 219 65 65 66
email: info@airturquoise.ch
homepage: www.para-test.com



ISO 9001:2000